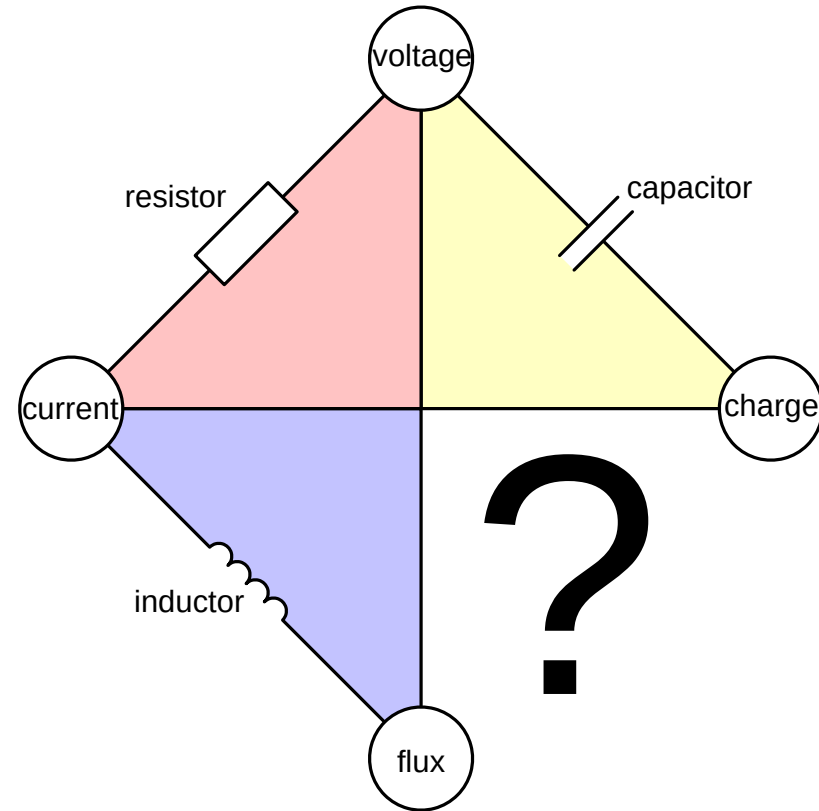
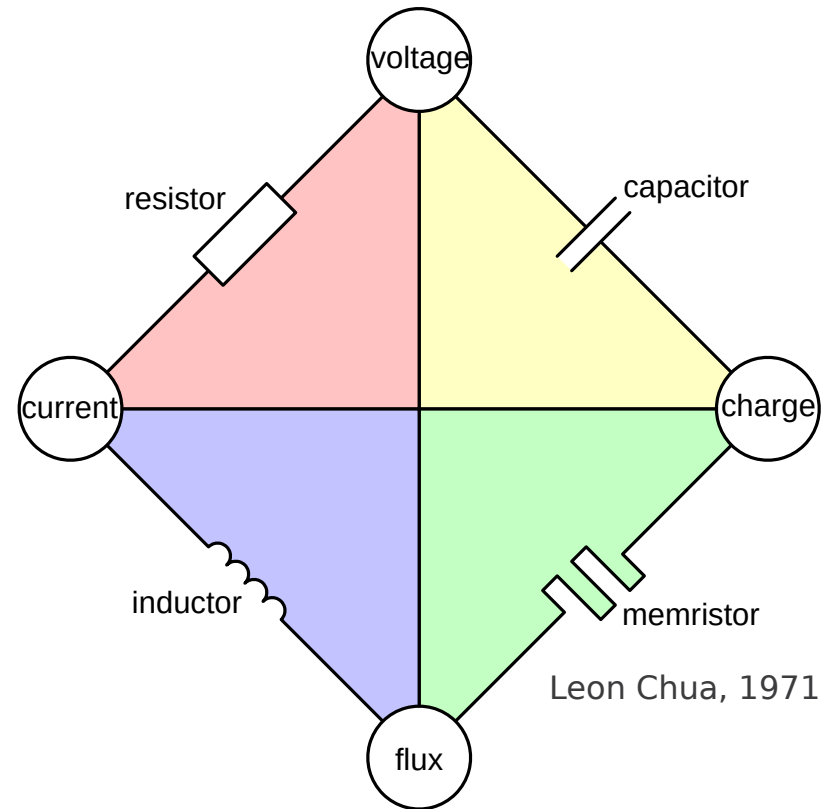
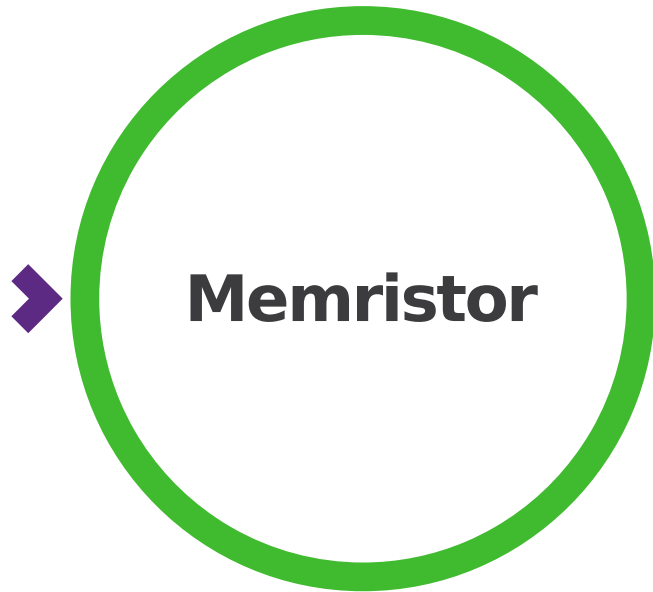


Stateless encoding in V4L2

Andrzej Pietrasiewicz
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➤ **Missing
element?**







	DECODER	ENCODER
STATEFUL		
STATELESS		



	DECODER	ENCODER
STATEFUL		
STATELESS		

Stateless encoders are coming to Linux

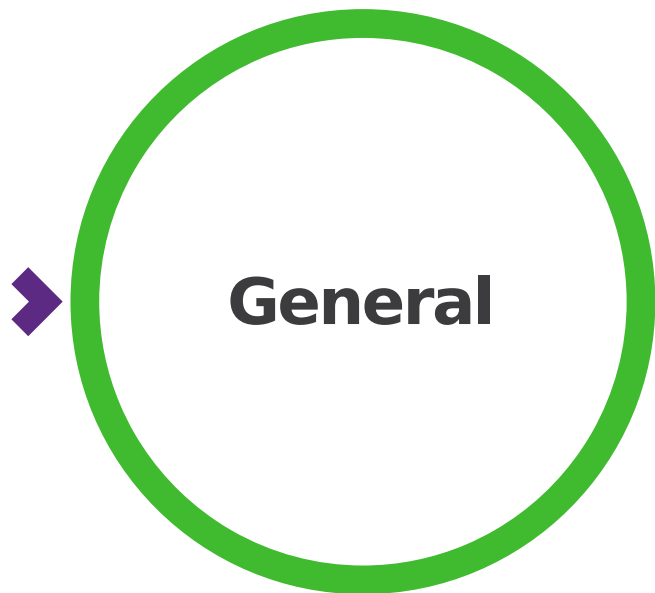
Agenda

- Definitions
- uAPI
- Rate control
- Future
- Q&A

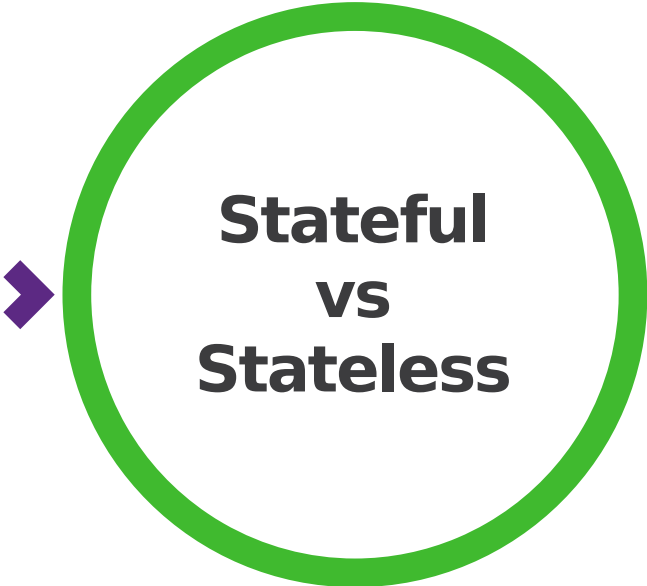


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Definitions



- CoDec
- mem2mem



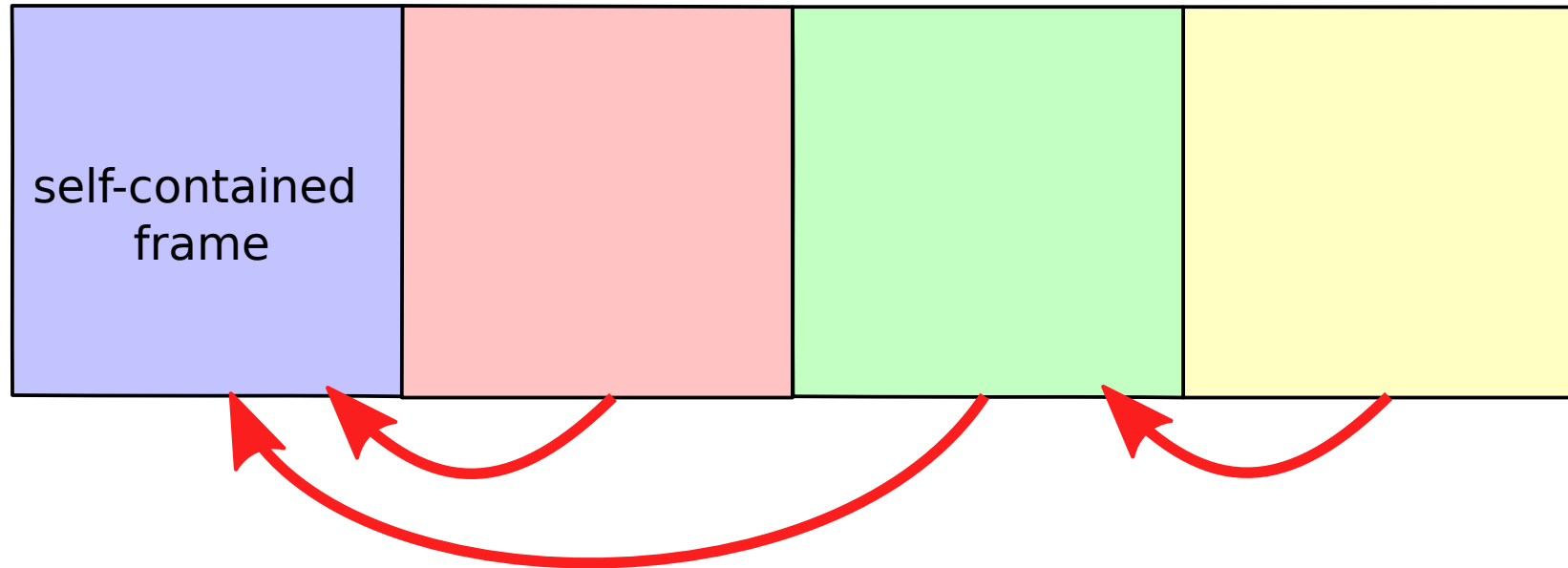
Stateful vs Stateless

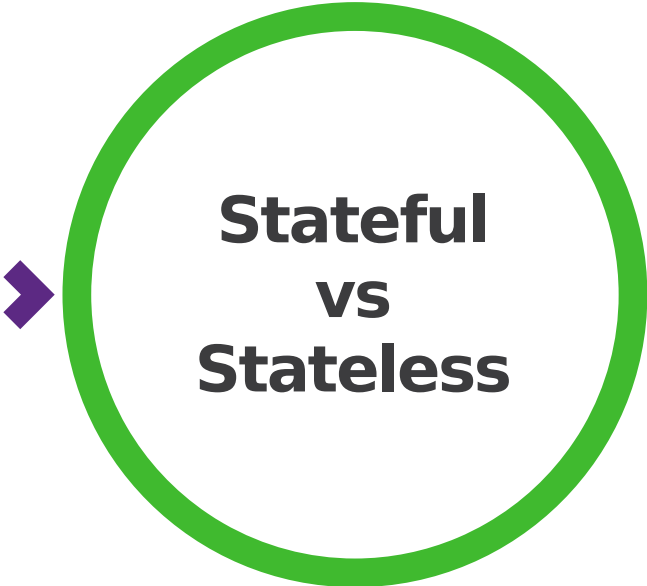
Stateful	Stateless
State kept and maintained in hardware	State kept and maintained outside hardware

So what?



Reference frames





Stateful vs Stateless

Stateful	Stateless
More complex hw	Less complex hw
Sw needs to interact with codec firmware	More registers to cope with
More expensive context change	Less expensive context change
Less flexibility	More flexibility

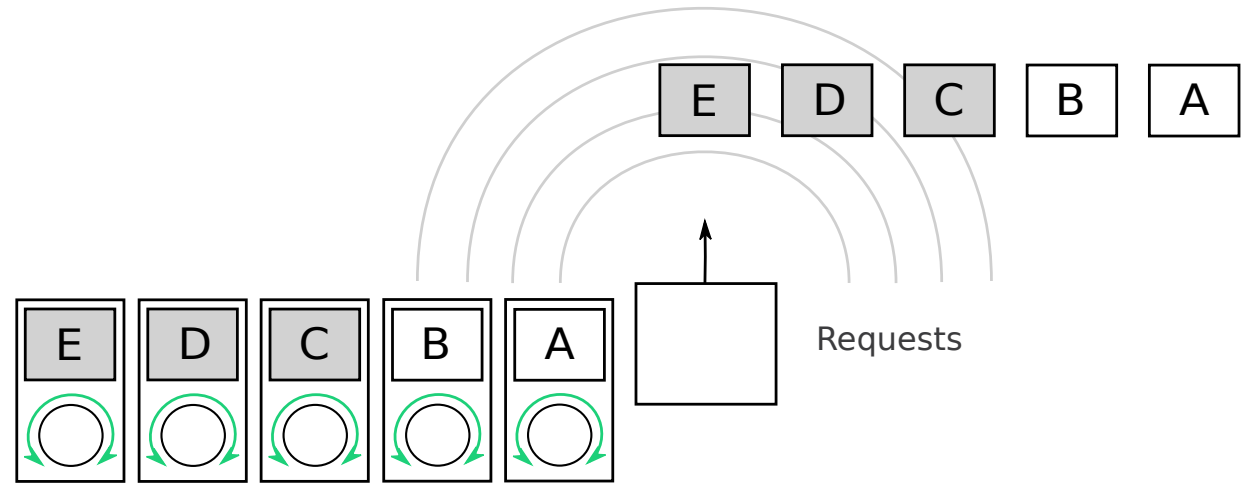
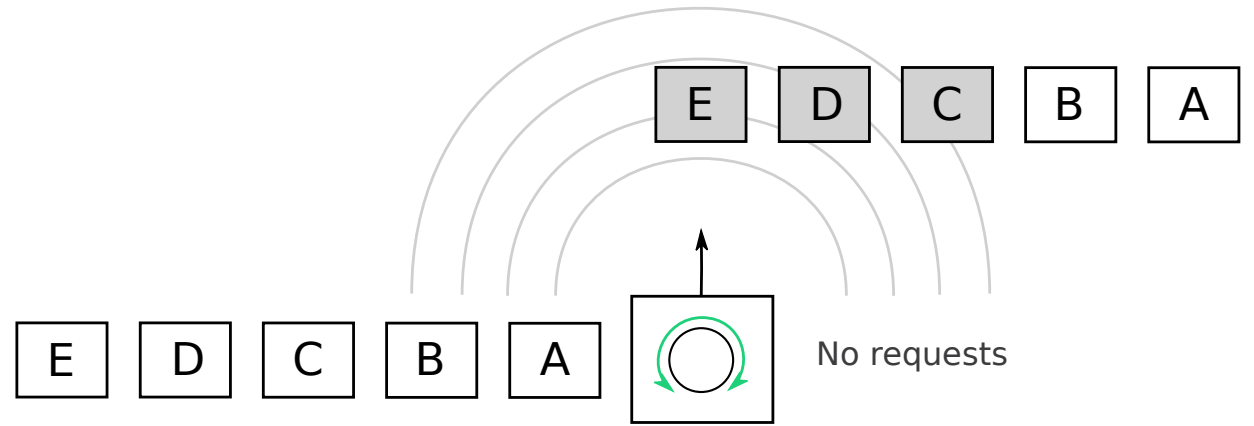


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uAPI

First encoders

- 2020: H.264
 - <https://github.com/bootlin/linux/tree/hantro/h264-encoding-v5.11>
 - <https://github.com/bootlin/v4l2-hantro-h264-encoder>
- 2023: VP8
 - <https://lore.kernel.org/linux-arm-kernel/20230309125651.23911-1-andrzej.p@collabora.com/T/>
 - <https://gitlab.collabora.com/linux/for-upstream/-/tree/vp8-rfc-v6.4-rc6>
 - https://gitlab.freedesktop.org/gstreamer/gstreamer/-/merge_requests/3736





```
ioctl(media_fd, MEDIA_IOC_REQUEST_ALLOC, &request_fd);

struct v4l2_ext_controls ext_ctrls;
struct v4l2_ext_control ctrls[1];
struct v4l2_ctrl_vp8_encode_params params;

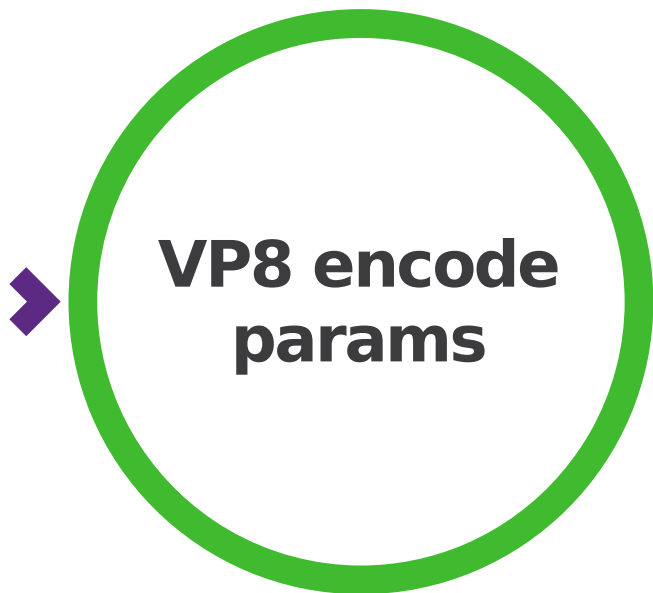
ext_ctrls.controls = ctrls;
ext_ctrls.count = 1;

ctrls[0].id = V4L2_CID_STATELESS_VP8_ENCODE_PARAMS;
ctrls[0].ptr = &params;
ctrls[0].size = sizeof(params);

ext_ctrls.which = V4L2_CTRL_WHICH_REQUEST_VAL;
ext_ctrls.request_fd = request_fd;

ioctl(video_fd, VIDIOC_S_EXT_CTRLs, &ext_ctrls);

ioctl(request_fd, MEDIA_REQUEST_IOC_QUEUE, NULL);
```



```
struct v4l2_ctrl_vp8_encode_params {  
    __u32 flags;  
    __u8 frame_type;  
    __u8 color_space;  
    __u8 clamping_type;  
    __u8 loop_filter_type;  
    __u8 loop_filter_level;  
    __u8 sharpness_level;  
    __u8 log2_nbr_of_dct_partitions;  
    __u8 prob_intra;  
    __u8 prob_last;  
    __u8 prob_gf;  
    __u8 copy_buffer_to_golden;  
    __u8 copy_buffer_to_alternate;  
    __u8 reference_type;  
};
```

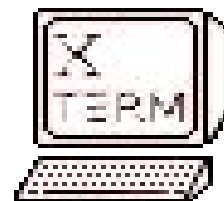
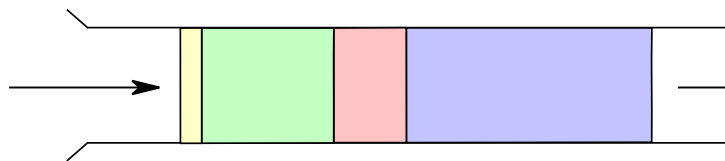
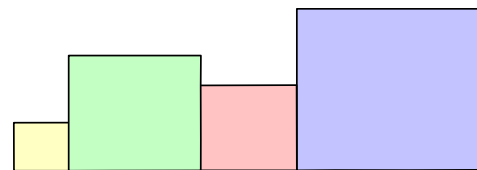
* Subject to change



Rate control



Encoder perspective



Decoder perspective

Rate control strategies

- Constant QP
- Constant Bitrate
- Average Bitrate
- ?



VP8 QP

```
struct v4l2_ext_controls ext_ctrls;  
struct v4l2_ext_control ctrls[1];
```

```
ext_ctrls.controls = ctrls;  
ext_ctrls.count = 1;
```

```
ctrls[0].id = V4L2_CID_STATELESS_VP8_ENCODE_QP;  
ctrls[0].value = fixed_qp;
```

```
ext_ctrls.which = V4L2_CTRL_WHICH_REQUEST_VAL;  
ext_ctrls.request_fd = request_fd;
```

```
ioctl(video_fd, VIDIOC_S_EXT_CTRLs, &ext_ctrls);
```

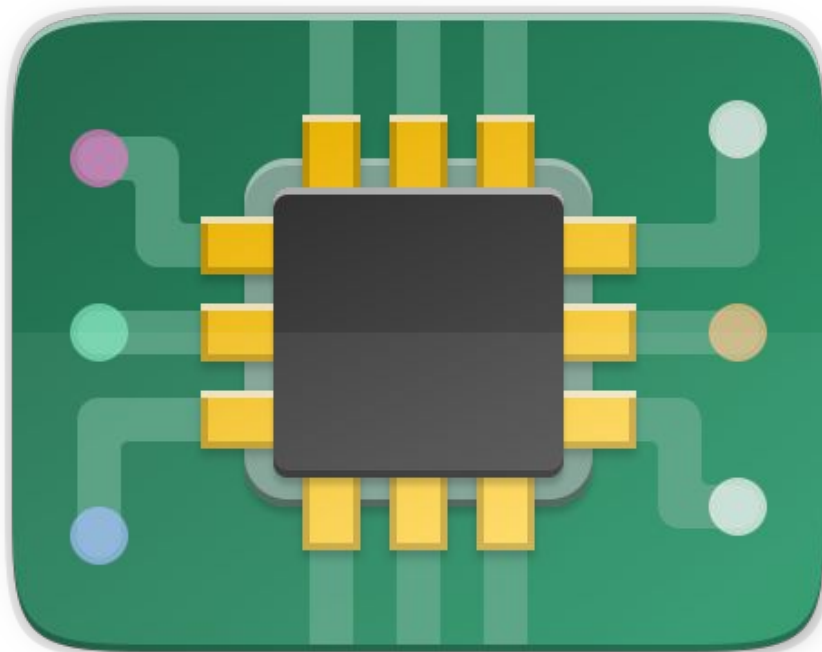
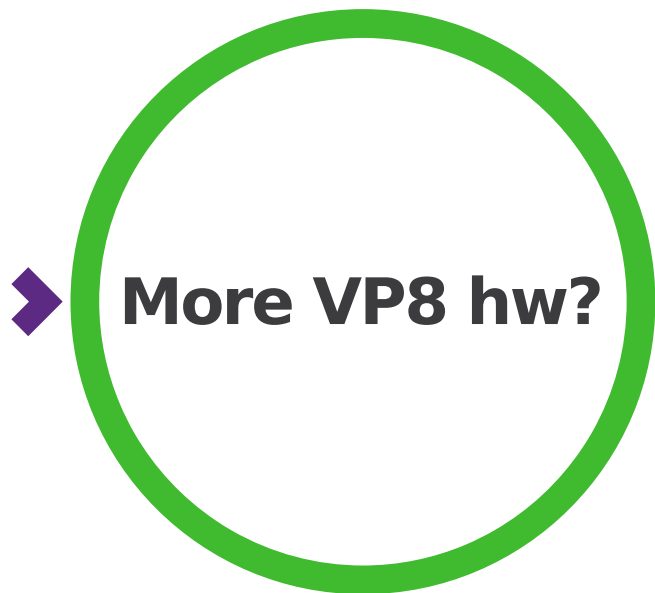
* Subject to change





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Future



Media Summit 26th Jun 2023

- 2 drivers rule?
- Frame header assembled in the kernel
- uAPI should support 3 reference frames
- Rate control:
 - Per-frame constant QP
 - Maybe have in-kernel algorithm for all encoders to use
 - Maybe support hardware-assisted rate control

AI?

- Improve encoders
 - Reference frame selection
 - Rate control
- Eliminate encoders 🤖
 - Make guesses



Thank you!



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